

Control Engineering

Poles/Zeros & Time Response using Scilab

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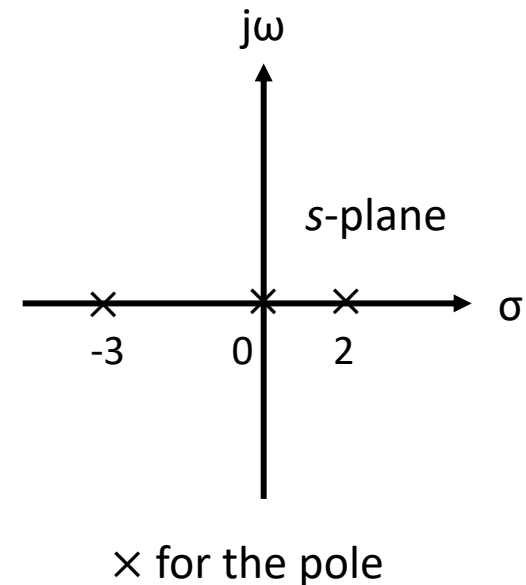
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Concept of Poles & Zeros

Poles:

1. Values of the Laplace transform variable, s , that cause the transfer function to become infinite,
 - The roots of the characteristic polynomial in the denominator
 - $\{0, -3\}$
2. Any **roots of the denominator** of the transfer function that are **common to roots of the numerator**
 - If a factor of the denominator can be canceled by the same factor in the numerator, the root of this factor no longer causes the transfer function to become infinite.
 - $\{2\}$

$$\frac{(s - 2)}{s(s - 2)(s + 3)}$$

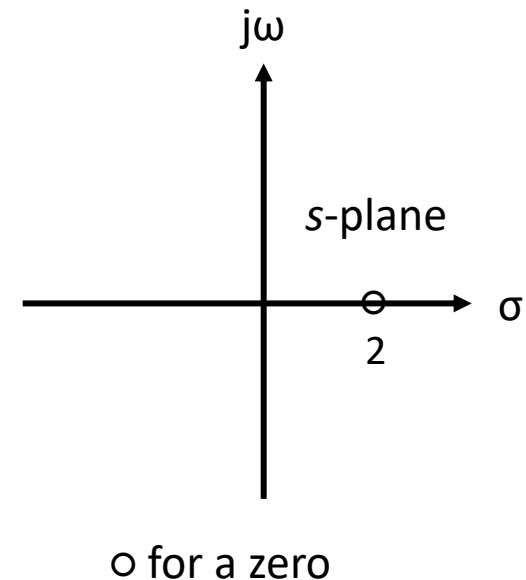


Concept of Poles & Zeros

Zeros:

1. The values of the Laplace transform variable, s , that cause the transfer function to become zero, or
 - The roots of the numerator are values of s that make the transfer function zero and are thus zeros
 - {2}
2. Any roots of the numerator of the transfer function that are **common to roots of the denominator**.
 - In control systems, the root of the canceled factor in the numerator as a zero even though the transfer function will not be zero at the value.

$$\frac{(s - 2)}{2s(s + 3)}$$



Scilab: Poles and Zeros of a 1st Order System

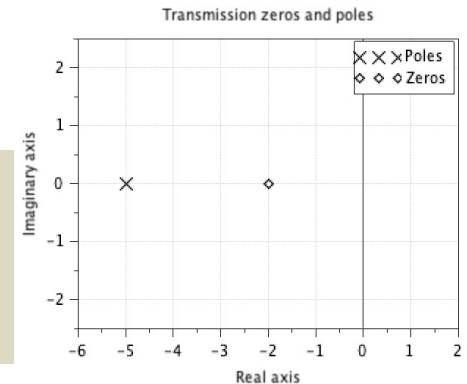
Given the transfer function $G(s) = \frac{(s + 2)}{(s + 5)}$

- a pole exists at $s = -5$, and
- a zero exists at -2 .

```

--> s=poly(0, 's');
--> n=[2+s];
--> d=[5+s];
--> h=syslin('c',n./d);
--> plzr(h)
    
```

To see the properties of the poles and zeros, we find the unit step response:



$$C(s) = \frac{s + 2}{s(s + 5)} = \frac{A}{s} + \frac{B}{s + 5}$$

Xcos

$$= \frac{2/5}{s} + \frac{3/5}{s + 5}$$

```

--> t=0:0.01:2;
--> x=2/5;
--> y=3/5*exp(-5*t);
--> z=2/5+3/5*exp(-5*t);
--> plot(t,x,'+-',t,y,'o-',t,z,'r-');
--> legend('forced response','natural response','response');
--> xlabel('time (sec)')
    
```

Time response:

$$c(t) = \frac{2}{5} + \frac{3}{5}e^{-5t}$$

Forced response

Natural response

